Amendments to the Claims:

Applicants have amended claims 1-4, 8, 9, and 11, and added new claims 12-20. This listing of claims will replace all prior versions, and listings of claims in the application:

Listing of Claims:

l	1. (Currently Amended) A method of simulating relative motion of objects
2	in computer animation comprising the steps of:
3	providing a motion of a kinematic object, where the kinematic object is an
4	element of a computer animation display;
5	providing at least one dynamic object associated with said kinematic object,
6	where said at least one dynamic object is another element of the computer animation display and
7	where motions motion of said at least one dynamic object are based on is influenced by the
8	motion of the kinematic object, wherein the motion of said at least one dynamic object is
9	simulated using a physically-based numerical technique;
10	selectively manipulating the motions of said at least one dynamic object to
11	simulate physical motion; and
12	manipulating the motion of said at least one dynamic object in response to the
13	motion of the kinematic object when the motion of the kinematic object exceeds a predetermined
14	threshold; and
15	displaying the elements of the computer animation display, including associated
16	motions of said elements.
1	2. (Currently Amended) A method of simulating relative motion of objects
2	according to claim 1 wherein said step of selectively manipulating the motion of said at least one
3	dynamic object comprises compensating for unreasonable motions of said at least one dynamic
4	object when the motion of the kinematic object undergoes exaggerated motion exceeds the
5	predetermined threshold.

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reference point on said kinematic object.

1 3. (Currently Amended) A method of simulating relative motion of objects according to claim 2 wherein said exaggerated the motion of said at least one dynamic object is 2 3 manipulated when the motion of the kinematic object comprises accelerations that are unrealistic 4 for humans. (Currently Amended) A method of simulating relative motion of objects 4. 1 2 according to claim 2 wherein said step of selectively the manipulating comprises compensating for the unreasonable motions motion of said at least one dynamic object when the kinematic 3 object undergoes accelerated motions above a predetermined limit. 4 (Original) A method of simulating relative motion of objects according to 1 5. claim 1 wherein said kinematic object is an animated character and said at least one dynamic 2 3 object is coupled to the animated character. (Original) A method of simulating relative motion of objects according to 6. 1 2 claim 5 wherein said at least one dynamic object is a representation of hair attached to the 3 animated character. (Original) A method of simulating relative motion of objects according to 1 7. 2 claim 5 wherein said at least one dynamic object is a representation of clothing attached to the 3 animated character. (Currently Amended) A method of simulating relative motion of objects 1 8. according to claim 1 wherein said at least one dynamic object comprises a first set of dynamic 2 objects and a second set of dynamic objects and said step of selectively manipulating the motions 3 motion of said at least one dynamic object comprises selectively manipulating motions of said 4 first set of dynamic objects with respect to a first reference point on said kinematic object and 5 selectively manipulating motions of said second set of dynamic objects with respect to a second 6

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9. (Currently Amended) A method of simulating relative motion of objects
according to claim 1 wherein said at least one dynamic object comprises a plurality of dynamic
objects coupled to a plurality of reference points on said kinematic object and wherein said step
of selectively manipulating the motions motion of said at least one dynamic object comprises
manipulating the motions of each of said plurality of dynamic objects with respect to said
plurality of reference points coupled thereto.
10. (Original) A method of simulating relative motion of objects according to
claim 9 wherein said kinematic object is an animated character and said plurality of dynamic
objects are coupled to the animated character and said plurality of reference points are different
points on the animated character.
11. (Currently Amended) A method of simulating relative motion of objects
according to claim 9 wherein said step of selectively the manipulating comprises compensating
for unreasonable motions of said plurality of dynamic objects when the kinematic object
undergoes exaggerated motion.
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12. (New) The method of claim 1 wherein manipulating the motion of said at
least one dynamic object comprises manipulating the motion of the said at least one dynamic
object when acceleration of the kinematic object exceeds the predetermined threshold.
13. (New) A computer animation system comprising:
a processor;
a display;
wherein the processor is configured to:
receive information specifying motion for a kinematic object;
compute motion for a dynamic object based upon the motion of the
kinematic object, wherein the motion of the dynamic object is specified using a physically-based
numerical technique; and

9	manipulate the motion of the dynamic object in response to the motion of
10	the kinematic object when the motion of the kinematic object exceeds a predetermined threshold;
11	and
12	wherein the display is configured to display the kinematic object and the dynamic
13	object and their associated motions.
1	14. (New) The method of claim 13 wherein the processor is configured to
2	manipulate the motion of the dynamic object when acceleration of the kinematic object exceeds
3	the predetermined threshold.
5	the production miles threshold.
1	15. (New) The method of claim 13 wherein the kinematic object represents an
2	animated character and the dynamic object represents a hair attached to the animated character.
1	16. (New) The method of claim 13 wherein the kinematic object represent an
2	animated character and the dynamic object represents clothing attached to the animated
3	character.
5	Character.
1	17. (New) A computer animation apparatus comprising:
2	means for receiving information specifying motion for a kinematic object;
3	means for computing motion for a dynamic object based upon the motion of the
4	kinematic object, wherein the motion of the dynamic object is specified using a physically-based
5	numerical technique;
6	means for manipulating the motion of the dynamic object in response to the
7	motion of the kinematic object when the motion of the kinematic object exceeds a predetermined
8	threshold; and
9	means for displaying the kinematic object and the dynamic object and their
10	associated motions.
1	18. (New) A computer program product stored on a computer-readable
2	storage medium for simulating relative motion of objects, the computer program product
3	comprising:

4	code for receiving information specifying motion for a kinematic object;
5	code for computing motion for a dynamic object based upon the motion of the
6	kinematic object, wherein the motion of the dynamic object is specified using a physically-based
7	numerical technique;
8	code for manipulating the motion of the dynamic object in response to the motion
9	of the kinematic object when the motion of the kinematic object exceeds a predetermined
10	threshold; and
11	code for displaying the kinematic object and the dynamic object and their
12	associated motions.
1	19. (New) A computer-implemented method of simulating relative motion of
2	objects in computer animation, the method comprising:
3	receiving information specifying motion for a kinematic object;
4	computing motion for a dynamic object based upon the motion of the kinematic
5	object, wherein the motion of the dynamic object is specified using a physically-based numerical
6	technique; and
7	manipulating the motion of the dynamic object in response to the motion of the
8	kinematic object when the motion of the kinematic object exceeds a predetermined threshold.
1	20. (New) The method of claim 19 wherein manipulating the motion of the
2	dynamic object comprises manipulating the motion of the dynamic object when acceleration of
3	the kinematic object exceeds the predetermined threshold.